

Takumi **Shinohara**, Ph.D.

Visiting Researcher

School of Integrated Design Engineering,
Faculty of Science and Technology, Keio University
3-14-1 Hiyoshi, Kohoku-ku, Yokohama, Kanagawa 223-8522, Japan

✉ ye.5.takt.s@gmail.com |  [Takumi Shinohara](#) |  [Takumi Shinohara](#)



Education

- | | |
|--------------------------|--|
| Sep. 2021 –
Sep. 2024 | Ph.D. in Engineering of Keio University, Japan
Thesis Title: <i>Secure state estimation under sensor attacks</i>
Advisor: Prof. Toru Namerikawa |
| Apr. 2016 –
Mar. 2018 | Master in Engineering of Keio University, Japan
Thesis Title: <i>Zero-stealthy attacks in cyber-physical systems and secure state estimation in adversarial environments</i>
Advisor: Prof. Toru Namerikawa |
| Apr. 2012 –
Mar. 2016 | Bachelor in Engineering of Keio University, Japan
Thesis Title: <i>SLAM problem for UAV with considering computational load and unordinary observations</i>
Advisor: Prof. Toru Namerikawa |

Employment

- | | |
|------------------------|--|
| Apr. 2018 –
present | Consultant, Mitsubishi Research Institute, Inc. , Japan
<i>Research, study, and consult on the cybersecurity policy for the Japanese Government (e.g., METI, MIC, and NISC) and consult private companies with cybersecurity issues.</i> |
|------------------------|--|

List of Publications

I. Journal Articles

- [1] [Takumi Shinohara](#) and Toru Namerikawa, "Optimal security investment problem for secure state estimation on cyber-physical systems," *IEEE Transactions on Automatic Control* (accepted, to appear in 2025).
- [2] [Takumi Shinohara](#) and Toru Namerikawa, "Optimal resilient sensor placement problem for secure state estimation," *Automatica*, vol. 160, 111454, 2024.

- [3] Takumi Shinohara and Toru Namerikawa, "Distributed secure state estimation with a priori sparsity information," *IET Control Theory & Applications*, vol. 16, no. 11, pp. 1086–1097, 2022.
- [4] Takumi Shinohara, Toru Namerikawa, and Zhihua Qu, "Resilient reinforcement in secure state estimation against sensor attacks with a priori information," *IEEE Transactions on Automatic Control*, vol. 64, no. 12, pp. 5024–5038, 2019.
- [5] Takumi Shinohara and Toru Namerikawa, "Reach set-based secure state estimation against sensor attacks with interval hull approximation," *SICE Journal of Control, Measurement, and System Integration*, vol. 11, no. 5, pp. 399–408, 2018.
- [6] Takumi Shinohara and Toru Namerikawa, "Perfect stealthy attacks in cyber-physical systems," *Transactions of the Society of Instrument and Control Engineers*, vol. 54, no. 3, pp. 309–319, 2018. (in Japanese)
- [7] Takumi Shinohara and Toru Namerikawa, "On the vulnerabilities due to manipulative zero-stealthy attacks in cyber-physical systems," *SICE Journal of Control, Measurement, and System Integration*, vol. 10, no. 6, pp. 563–570, 2017.
- [8] Takashi Irita, Takumi Shinohara and Toru Namerikawa, "Detection of replay attack on smart grid with code signal and bargaining game," *Transactions of the Society of Instrument and Control Engineers*, vol. 52, no. 9, pp. 498–506, 2016. (in Japanese)

II. Referred Conference Papers

- [1] Takumi Shinohara and Toru Namerikawa, "Security measure implementation for distributed state estimation," in *Proc. 5th IFAC Workshop on Cyber-Physical Human Systems*, Antalya, Türkiye, 2024. (accepted, to be presented)
- [2] Takumi Shinohara and Toru Namerikawa, "Secure state estimation for multi-agent systems: On the relationship between the number of agents and system resilience," in *Proc. 2023 American Control Conference*, San Diego, CA, 2023, pp. 1006–1011.
- [3] Takumi Shinohara and Toru Namerikawa, "Reach set-based attack resilient state estimation against omniscient adversaries," in *Proc. 2018 American Control Conference*, Milwaukee, WI, 2018, pp. 5813–5818.
- [4] Takumi Shinohara and Toru Namerikawa, "Manipulative zero-stealthy attacks in cyber-physical systems: Existence space of feasible attack objectives," in *Proc. 1st IEEE Conference on Control Technology and Applications*, Kohala Coast, HI, 2017, pp. 1123–1128.
- [5] Takumi Shinohara and Toru Namerikawa, "SLAM for a small UAV with compensation for unordinary observations and convergence analysis," in *Proc. 2016 55th Annual Conference of the Society of Instrument and Control Engineers of Japan (SICE)*, Tsukuba, Japan, 2016, pp. 1252–1257.